

TM-2-A7-PB0(J0) Torque Motor

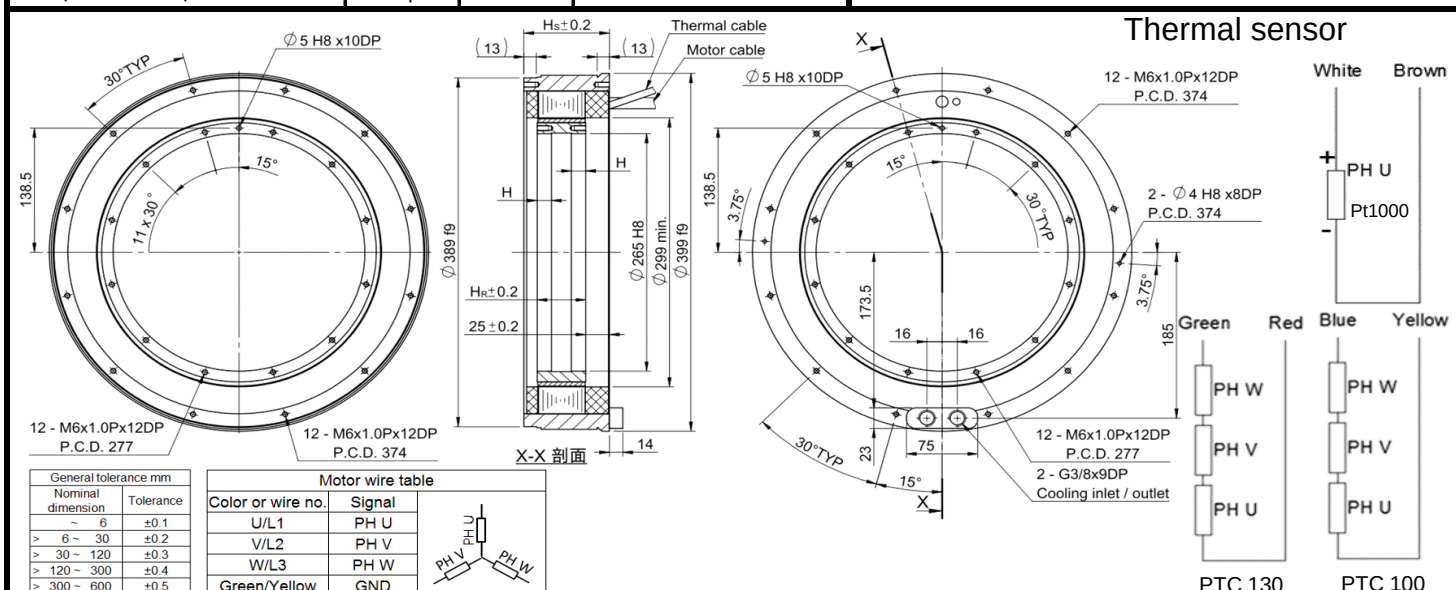
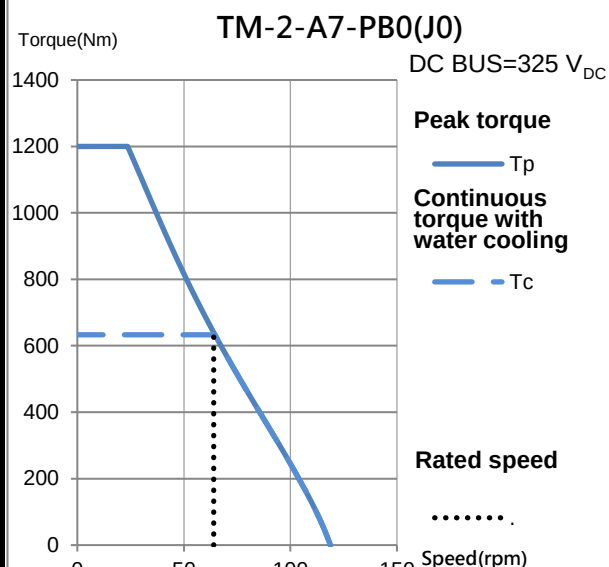
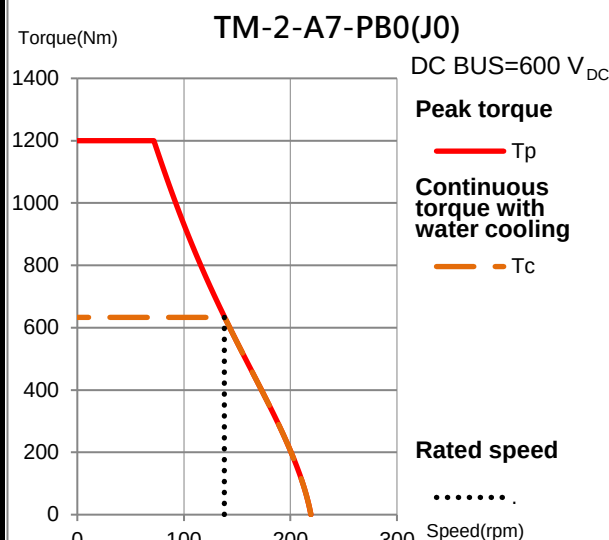
Electrical specifications

Winding code : PB0	Symbol	Unit	Water cooling
Continuous torque	T_c	Nm	633
Continuous current	I_c	A_{rms}	23
Stall torque	T_s	Nm	518
Stall current	I_s	A_{rms}	18.4
Peak torque(for 1sec.)	T_p	Nm	1200
Peak current(for 1sec.)	I_p	A_{rms}	52
Torque constant	K_t	Nm/Arms	29.1
Electrical time constant	T_e	ms	6.8
Resistance (line to line at 25°C)	R_{25}	Ω	3.6
Inductance (line to line)	L	mH	24.3
Number of poles	2p		66
Back emf constant (line to line)	K_v	Vrms/rad/s	16.8
Motor constant (at 25°C)	K_m	Nm/ $\sqrt{W}$	12.53
Thermal resistance	R_{th}	K/W	0.037
Thermal sensor			PTC 100+PTC 130+Pt1000
Max. DC BUS		V_{DC}	750
Inertia of rotor	J	kgm^2	0.151
Thermal time constant	T_{th}	s	130
Max. continuous power dissipation	P_c	W	4030
Max. peak power dissipation	P_p	W	20604
Rated speed(at 600VDC)		rpm	138

Mechanical specifications

	Symbol	Unit	Water cooling
Mass of rotor	M_r	kg	7.6
Mass of stator	M_s	kg	33.5
Height of stator	H_s	mm	110
Height of rotor	H_r	mm	71
Length of rotor centring fit	H	mm	15
Water temperture difference for P_c	$\Delta\theta$	K	5
Minimum water flow	q	l/min	11.6
Max. pressure drop	Δp	bar	1

T-N curve



Except dimensions, all the specifications in the table are in $\pm 10\%$ of tolerance

Version: 2.00

This drawing is only for reference, detail dimensions please refer to approval drawing.

Date: 2023/6/8